STROKE BUSH

The NB stroke bush is a linear and rotational motion mechanism utilizing the rotational motion of ball elements between an outer cylinder and a shaft. It is compact and can withstand high loading.

The retainer is made of a light metal alloy with high wear resistance. Smooth motion is achieved under high-speed and high-acceleration conditions. Although the linear motion is limited to a specific stroke length, the combined

rotation and stroke motion is achieved with very little frictional resistance. The NB stroke bush can be conveniently used in a variety of applications.

STRUCTURE AND ADVANTAGES

The retainer in the NB stroke bush positions the ball elements in a zigzag arrangement. The inner surface of the outer cylinder is finished by precision grinding, resulting in smooth motion of the ball elements. Each of the ball elements is held in a separate hole and smooth motion is achieved for both rotational motion and linear motion. The retainer moves half the length of the linear motion, therefore, the stroke length is limited to approximately twice the length the retainer can travel within the outer cylinder.

High Precision

NR

High-carbon chromium bearing steel is used for the outer cylinder. It is heat treated and ground to achieve high rigidity and accuracy.

Figure E-1 Structure of SR Stroke Bush

Ease of Mounting and Replacement

The highly accurate fabrication of the NB stroke bush results in uniform dimensions, facilitating parts replacement and housing fabrication.

Light Weight and Space Saving

The use of an aluminum alloy for the retainer and the thin-wall outer cylinder makes the NB stroke bush light weight and compact.

Lubrication

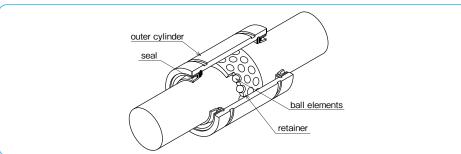
One lubrication hole is provided on each oil groove of the outer cylinder, making it easy to lubricate the SR stroke bush.

Figure E-2 Outer Cylinder Measurement Points

-0-0-0

P. W

W



ACCURACY

The accuracies of the SR stroke bush are stated in the dimension tables. Since the outer cylinder deforms due to tension from the retaining ring, the dimension of the outer cylinder is an average value at points P, where calculated using the following equation:

W: the distance from the end of the outer cylinder to measurement point P L: the length of the outer cylinder

E-2

FIT

The fits generally used between the shaft and the housing are listed in Table E-1. The inner contact diameters of the SR stroke bush are listed in the dimension tables. The shaft diameter tolerance should be selected to achieve the desired amount of radial clearance (see Table E-2). Please pay attention that high-speed linear motion can cause the retainer to slip due to inertial force. In selecting a shaft, please take note of:

Hardness: 58HRC or more (refer to hardness coefficient on page Eng-5) recommended Surface Roughness: less than Ra0.4 recommended

RATED LOAD AND RATED LIFE

The relationship between the rated load and life of the stroke bush is expressed as follows:

$$L = \left(\frac{f_{H} \cdot f_{T} \cdot f_{C}}{f_{W}} \cdot \frac{C}{P}\right)^{2}$$

L: rated life (10⁶ rotations) fH: hardness coefficient fr: temperature coefficient fc: contact coefficient fw: applied load coefficient C: basic dynamic load rating (N) P: applied load (N) %Refer to page Eng-5 for the coefficients.

ALLOWABLE SPEED FOR COMBINED ROTATION AND STROKE MOTION

The allowable speed for combined rotation and stroke motion is obtained from the following equation:

DN≧dm ⋅ n+10 ⋅ S ⋅ n₁

USE AND HANDLING PRECAUTIONS

Maximum Stroke

The maximum stroke in the dimension table is the stroke limit.

Retainer Slippage

The retainer can slip under high-speed motion, vertical application, unbalanced-loading, and vibrating conditions. It is suggested that the stroke to be set as a 80% of the maximum stroke in the dimension table. It is also recommended that the bush be cycled to perform the maximum stroke several times, so that the retainer returns to its central position.

Table E-1

normal opera	ting condition	vertical use or highly accurate case					
shaft	housing	shaft	housing				
k5,m5	H6,H7	n5,p6	J6,J7				

Table E-2 Radial	Clearance	Negative Limit
------------------	-----------	----------------

part number	limit (µm)
6	- 2
8~10	- 3
12~16	- 4
20~30	- 5
35~50	- 6
60~80	- 8
100	-10

•For combined rotation and stroke motion

$$L_{h} = \frac{10^{6} \cdot L}{60\sqrt{(dm \cdot n)^{2} + (10 \cdot S \cdot n_{1})^{2}}/dm}$$

For stroke motion

$$h = \frac{10^6 \cdot L}{600 \cdot S \cdot n_1 / (\pi \cdot dm)}$$

Lh: life time (hr) S: stroke length (mm) n: revolutions per min. (rpm) n: number of cycles per minute (cpm) dm: ball pitch diameter (mm) $\doteq 1.15$ dr

The value of DN is given as follows depending on the lubrication method.

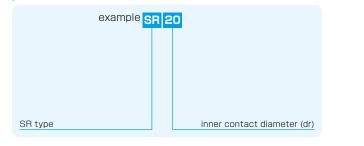
for oil lubrication	DN=600,000
for grease lubrication	DN=300,000
noten≦5,000 S · n1≦50	,000

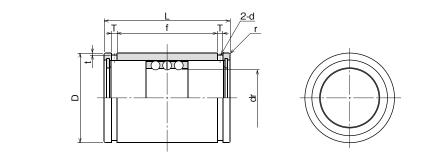
E-3

SR TYPE



part number structure



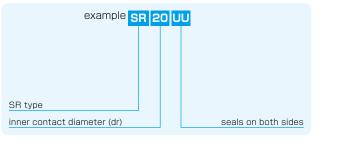


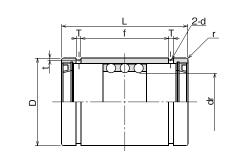
		maximum			major dimensions basi									basic loa	ad rating		
port pu	mbor	stroke	number	c	ir	[2	1	-	f	Т	t	d	r	dynamic	static	mass
part nu	innber		of rows		tolerance		tolerance		tolerance						С	Co	
		mm		mm	μm	mm	μm	mm	mm	mm	mm	mm	mm	mm	N	Ν	g
SR	6	19	3	6	+22	12	0	20		11.3	1.1	0.5	1	0.5	216	147	8.9
SR	8	24	3	8	+22 $+13$	15	-11	24		17.1	1.5	0.5	1.2	0.5	343	245	15.6
SR	10	30	3	10	T 13	19	0	30	0	22.7	1.5	0.5	1.2	0.5	637	461	28.8
SR	12	32	3	12	+27	23	-13	32	-0.2	24.5	1.5	0.5	1.2	0.5	1,070	813	42
SR	16	40	3	16	+16	28	-13	37		29.1	1.5	0.7	1.3	0.5	1,180	990	71
SR	20	50	3	20	+33	32	0	45		35.8	2	0.7	1.5	0.5	1,260	1,170	99
SR	25	50	3	25		37	-	45		35.8	2	0.7	1.6	1	1,330	1,330	117
SR	30	82	3	30	+20	45	-16	65		53.5	2.5	1	2	1	2,990	3,140	205
SR	35	92	3	35	1.44	52	0	70	0	58.5	2.5	1	2	1.5	3,140	3,530	329
SR	40	108	3	40	+41	60	v	80	-0.3	68.3	2.5	1	2	1.5	4,120	4,800	516
SR	50	138	3	50	+25	72	-19	100		86.4	3	1	2.5	1.5	5,540	6,910	827
SR	60	138	3	60	+49	85	0	100		86.4	3	1	2.5	2	5,980	8,230	1,240
SR	80	132	3	80	+30	110	-22	100	0	86	3	1.5	2.5	2	7,840	12,200	2,050
SR1	00	132	3	100	+58/+36	130	0/-25	100	-0.4	86	3	1.5	2.5	2	8,430	14,700	2,440
									-					-		1N≑0.	102kgf

SR-UU TYPE



part number structure





|--|

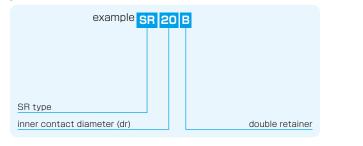
	maximum				_		major	dime	nsions		_	_	_	basic lo		
part number	stroke	number	c	lr	[D C	1	Ļ	f	Т	t	d	r	dynamic	static	mass
part number		of rows		tolerance		tolerance		tolerance						С	Co	
	mm		mm	μm	mm	μm	mm	mm	mm	mm	mm	mm	mm	N	N	g
SR 8UU	14	3	8	+22	15	0/-11	24		12.3	1.5	0.5	1.2	0.5	343	245	15.6
SR 10UU	16	3	10	+13	19	0	30	0	15.5	1.5	0.5	1.2	0.5	637	461	28.8
SR 12UU	18	3	12	+27	23	-13	32	-0.2	17.1	1.5	0.5	1.2	0.5	1,070	813	42
SR 16UU	26	3	16	+16	28	-13	37	-0.2	21.1	1.5	0.7	1.3	0.5	1,180	990	71
SR 20UU	36	3	20	+33	32	0	45		26.8	2	0.7	1.5	0.5	1,260	1,170	99
SR 25UU	36	3	25	+33 $+20$	37	-16	45		26.8	2	0.7	1.6	1	1,330	1,330	117
SR 30UU	68	3	30	720	45	-10	65		45.1	2.5	1	2	1	2,990	3,140	205
SR 35UU	76	3	35	+41	52	0	70	0	50.1	2.5	1	2	1.5	3,140	3,530	329
SR 40UU	91	3	40	+41 +25	60	0 	80	-0.3	59.9	2.5	1	2	1.5	4,120	4,800	516
SR 50UU	116	3	50	725	72	-19	100		77.4	3	1	2.5	1.5	5,540	6,910	827
SR 60UU	117	3	60	+49	85	0	100		77.4	3	1	2.5	2	5,980	8,230	1,240
SR 80UU	110	3	80	+30	110	-22	100	0	77	3	1.5	2.5	2	7,840	12,200	2,050
SR100UU	110	3	100	+58/+36	130	0/-25	100	-0.4	77	3	1.5	2.5	2	8,430	14,700	2,440
	1					•• ••		••••		-				0,.00	111-0	/

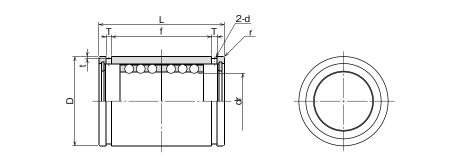
1N≒0.102kgf

SR-B TYPE



part number structure





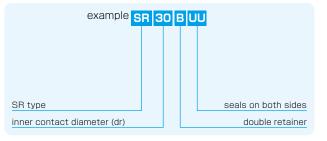
	maximum						major	dime	nsions					basic loa	ad rating	
nort number	stroke	number	c	ir	[C	I	L	f	Т	t	d	r	dynamic	static	mass
part number		of rows		tolerance		tolerance		tolerance						С	Co	
	mm		mm	μm	mm	μm	mm	mm	mm	mm	mm	mm	mm	Ν	Ν	g
SR 8B	8	6	8	+22	15	0/-11	24		17.1	1.5	0.5	1.2	0.5	549	490	16.8
SR 10B	8	6	10	+13	19	0	30	0	22.7	1.5	0.5	1.2	0.5	1,030	931	31.2
SR 12B	8	6	12	+27	23	-	32	-0.2	24.5	1.5	0.5	1.2	0.5	1,720	1,630	46
SR 16B	16	6	16	+16	28	-13	37	-0.2	29.1	1.5	0.7	1.3	0.5	1,910	1,980	75
SR 20B	20	6	20	+33	32	0	45		35.8	2	0.7	1.5	0.5	2,060	2,320	106
SR 25B	20	6	25	+33+20	37	-16	45		35.8	2	0.7	1.6	1	2,170	2,670	125
SR 30B	44	6	30	720	45	- 10	65		53.5	2.5	1	2	1	4,800	6,270	220
SR 35B	54	6	35	1.44	52	0	70	0	58.5	2.5	1	2	1.5	5,050	7,060	346
SR 40B	66	6	40	+41 +25	60	-19	80	-0.3	68.3	2.5	1	2	1.5	6,710	9,560	540
SR 50B	88	6	50	725	72	-19	100		86.4	3	1	2.5	1.5	8,970	13,800	862
SR 60B	88	6	60	+49	85	0	100	1	86.4	3	1	2.5	2	9,700	16,500	1,290
SR 80B	76	6	80	+30	110	-22	100	0	86	3	1.5	2.5	2	12,700	24,300	2,110
SR100B	76	6	100	+58/+36	130	0/-25	100	-0.4	86	3	1.5	2.5	2	13,700	29,400	2,520
															1N≐0	102kgf

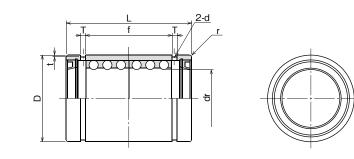
1N≑0.102kgf

SR-BUU TYPE



part number structure





	maximum			major dimensions									basic loa	ad rating		
nort number	stroke	number	c	ir	[2		L	f	Т	t	d	r	dynamic	static	mass
part number		of rows		tolerance		tolerance		tolerance						С	Co	
	mm		mm	μm	mm	μm	mm	mm	mm	mm	mm	mm	mm	N	N	g
SR 30BUU	30	6	30	+33/+20	45	0/-16	65		45.1	2.5	1	2	1	4,800	6,270	220
SR 35BUU	38	6	35	+41	52	0	70	0	50.1	2.5	1	2	1.5	5,050	7,060	346
SR 40BUU	49	6	40	+41+25	60	-19	80	-0.3	59.9	2.5	1	2	1.5	6,710	9,560	540
SR 50BUU	66	6	50	725	72	-19	100	-0.3	77.4	3	1	2.5	1.5	8,970	13,800	862
SR 60BUU	67	6	60	+49	85	0	100		77.4	3	1	2.5	2	9,700	16,500	1,290
SR 80BUU	54	6	80	+30	110	-22	100	0	77	3	1.5	2.5	2	12,700	24,300	2,110
SR100BUU	54	6	100	+58/+36	130	0/-25	100	-0.4	77	3	1.5	2.5	2	13,700	29,400	2,520

1N≒0.102kgf

E-6

SLIDE ROTARY BUSH SRE SERIES

The NB Slide Rotary Bush SRE Series provides rotary and linear motion functions. Linear motion with unlimited stroke and rotary motion are merged into a single bush resulting in great space saving compared with a combination of any conventional bearings. There are three types: standard, flange, and unit type with sizes ranging from 6 to 40.

STRUCTURE AND ADVANTAGES

NB Slide Rotary Bush features a special retainer fitted into cylindrical steel outer cylinder and is designed to guide steel balls for smooth circulation in its retainer. The retainer is also designed to rotate freely towards radial direction and offers smooth linear and rotary motions.

Smooth Operation

The inner surface of the outer cylinder allows smooth operation of linear and rotary motions while maintaining a uniform load distribution.

High Load Capacity

The use of comparatively large diameter steel balls enhances the load capacity.

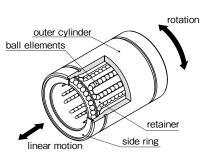
Smooth Rotation

The positioning of the steel balls in a cylindrical formation inside the retainer enables a smooth rotational motion regardless of the installation direction.

Complete Interchangeability

NB Slide Rotary series is completely interchangeable with SM type Slide Bush, SMK type Flanged Slide Bush and SMA(W) type, AK(W) type and SMP type.

Figure E-3 Structure of Slide Rotary Bush SRE type





RATED LIFE AND LOAD RATING

The rated life and load rating are defined as follows.

Rated Life

When a group of slide rotary bearings of the same type are used under the same conditions, the rated life is defined as the total number of rotations made without causing flaking by 90% of the bearings.

Basic Dynamic Load Rating

The basic dynamic load rating is defined as the load with a constant magnitude and direction at which a rated life of 10⁶ rotations can be achieved.

Basic Static Load Rating

The basic static load rating is defined as the load with a constant direction that would result in a certain contact stress at the mid-point of the rolling element and tracking surface that are experiencing the maximum stress.

Equation (1) gives the relation between the applied load and the rated life of the slide rotary bush.

L: rated life (10⁶ rotations) fH: hardness coefficient fr: temperature coefficient fc: contact coefficient fw: applied load coefficient C: basic dynamic load rating (N) P: applied load (N)

*Refer to page Eng-5 for the coefficients.

Since the slide rotary bush is used in applications with combined linear and rotary motions, the life time is obtained using Equations (2) and (3).

•When linear and rotary motions are combined

$$h = \frac{10^{6} \cdot L}{60\sqrt{(dm \cdot n)^{2} + (10 \cdot S \cdot n_{1})^{2}/dm}} \cdots (2)$$

•When only linear motion is involved

Lh: life time (hr) S: stroke length (mm) n: revolutions per minute (rpm) n1: number of cycles per minute (cpm) dm: ball pitch diameter (mm) = 1.15dr (dr is the inner contact diameter of the SRE series)

Calculation Example

The life of SRE20 type NB slide rotary bush is calculated based on the following conditions. Conditions

Motion: Linear and rotational combined Load: P=30N Stroke: S=200mm Revolutions per minute: n=15rpm Number of cycles per minute: n1=10cpm Shaft surface hardness: greater than 58 HRC

Operating temperature: room temperature Other: single shaft with single bush

Calculation

Basic dynamic load rating: C=647 N

Based on the above conditions, the life is calculated using the following coefficient values. Hardness coefficient $f_{H=1}$, Temperature coefficient $f_{T=1}$, Contact coefficient $f_{c=1}$ Applied load coefficient, fw=1.5

Rated life

$$L = \left(\frac{f_{H} \cdot f_{T} \cdot f_{C}}{f_{W}} \cdot \frac{C}{P}\right)^{3}$$

$$= \left(\frac{1 \times 1 \times 1}{1.5} \cdot \frac{647}{30}\right)^{3} = 2,972 \ (10^{6} \text{ rotations})$$
Life (in hours)

$$L_{h} = \frac{10^{6} \cdot L}{60\sqrt{(dm \cdot n)^{2} + (10 \cdot S \cdot n_{1})^{2}/dm}}$$

$$= \frac{10^{6} \times 2,972}{60\sqrt{(1.15 \times 20 \times 15)^{2} + (10 \times 200 \times 10)^{2}/(1.15 \times 20)}}$$

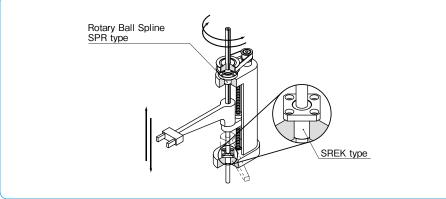
$$= 56,900 \ (h)$$

SLIDE ROTARY BUSH

E-9

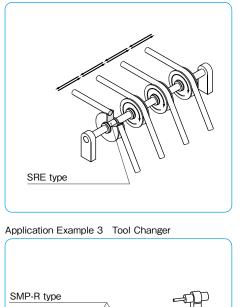
APPLICATION EXAMPLES

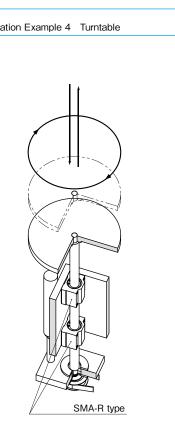
Application Example 1 Vertical Shaft Robot Arm



Application Example 2 Multiple Gearing Idler

Application Example 4 Turntable





USE AND HANDLING PRECAUTIONS

Shaft

Since the ball elements rotate on the shaft surface in the SRE type slide rotary bush, the accuracy and hardness of the shaft are important factors.

- Outer Diameter: A tolerance of g6 is recommended for smooth operation.
- Hardness: A hardness of greater than 58HRC is recommended for long life. If the hardness is less than 58 HRC, the life is calibrated using the hardness coefficient.

Surface Roughness: A roughness of less than RaO.4 is recommended.

Housing

An inner diameter tolerance of H7 is recommended for housing.

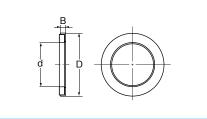
Lubrication

Lubrication is needed (1) to prevent heat fusing by reducing friction between the rolling elements and the tracking surface, (2) to reduce wear of the structural elements, and (3) to prevent rusting.

FELT SEAL

A felt seal FLM strengthens lubrication characteristics and extends relubrication period of the slide rotary bush.

Figure E-4 Felt Seal



Installation

The felt seal does not work as a retaining ring. Figure E-5 shows how to install the felt seal.

Lubrication affects both the performance and life of the bush. A lubrication method and a lubrication agent appropriate to the operating conditions should be selected. For oil lubrication, turbine oil (ISO standard VG32-68) is recommended. For grease lubrication, lithium soap based grease No. 2 is recommended. The replenishment interval depends on the operating conditions.

Oust Prevention

Dust and other contaminants affect the bush's lifetime and accuracy. Appropriate prevention methods are thus important.

Operating Temperature Range

The operating temperature is ranging from -20° C to 110°C. In case of operation at a temperature outside this range, please contact NB.

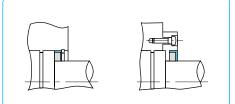
Retainer Material

The standard material of SRE Retainer is copper alloy (stainless steel for size 12). When requiring other material, please contact NB.

Table E-3 Felt Seal Dimensions

part number	major d	imensior	applicable	
part number	d	D	В	slide rotary bush
FLM 6	6	12	2	SRE 6
FLM 8	8	15	2	SRE 8
FLM 10	10	19	3	SRE 10
FLM 12	12	21	3	SRE 12
FLM 13	13	23	3	SRE 13
FLM 16	16	28	4	SRE 16
FLM 20	20	32	4	SRE 20
FLM 25	25	40	5	SRE 25
FLM 30	30	45	5	SRE 30
FLM 40	40	60	5	SRE 40

Figure E-5 Example of Installation



SRE TYPE

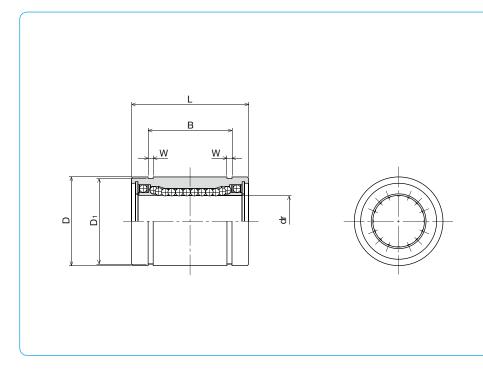


part number structure

example <mark>S</mark>	RE 25
SRE type	inner contact diameter (dr)

					major di	mensions			
part number	C	dr	1	D		L	В		
part number		tolerance		tolerance		tolerance		tolerance	
	mm	μm	mm	μm	mm	mm	mm	mm	
SRE 6	6	+4	12	0	19		13.5		
SRE 8	8	-5	15	-11	24		17.5		
SRE10	10	-5	19	0	29	0	22	0	
SRE12	12	1.0	21		30	° °	23	-0.2	
SRE13	13	+3	23	-13	32	-0.2	23		
SRE16	16	-6	28		37		26.5		
SRE20	20	1.2	32	0	42		30.5		
SRE25	25	+3	40	-16	59	0	41	0	
SRE30	30	/	45	-16	64	v	44.5	-	
SRE40	40	+3/-8	60	0/-19	80	-0.3	60.5	-0.3	

*If the inner contact diameter exceeds 40 mm, please contact NB.



		allowable	ad rating	basic loa		
part number	mass	revolutions	static	dynamic	D1	W
part number		per minute	Co	С		
	g	rpm	Ν	N	mm	mm
SRE 6	10	300	176	78	11.5	1.1
SRE 8	20	300	314	137	14.3	1.1
SRE10	39	300	372	157	18	1.3
SRE12	42	300	588	274	20	1.3
SRE13	56	300	686	323	22	1.3
SRE16	97	250	882	451	27	1.6
SRE20	133	250	1,180	647	30.5	1.6
SRE25	293	250	1,860	882	38	1.85
SRE30	371	200	2,650	1,180	43	1.85
SRE40	778	200	4,020	1,960	57	2.1

1N≑0.102kgf

SLIDE ROTARY BUSH

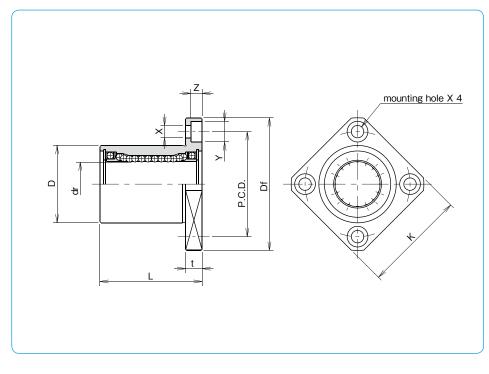
SREK TYPE - Square Flange type -



part number structure

exa	mple SREK 25
SREK type	inner contact diameter (dr)

					major dir	nensions		
part number		dr	1	D	L			flange
part number		tolerance		tolerance	±0.3	Df	ĸ	t
	mm	μm	mm	μm	mm	mm	mm	mm
SREK 6	6	+4	12	0	19	28	22	5
SREK 8	8	-5	15	-13	24	32	25	5
SREK10	10	-5	19		29	40	30	6
SREK12	12	1.2	21	0	30	42	32	6
SREK13	13	+3 -6	23	-16	32	43	34	6
SREK16	16	-0	28		37	48	37	6
SREK20	20	1.2	32	0	42	54	42	8
SREK25	25	+3 -7	40	-19	59	62	50	8
SREK30	30	-7	45	- 19	64	74	58	10



		allowable	ad rating	basic loa			
part number	mass	revolutions	static	dynamic	perpendicularity		
part number		per minute	Co	С		X×Y×Z	P.C.D.
	g	rpm	N	Ν	μm	mm	mm
SREK 6	21	300	176	78		3.5×6×3.1	20
SREK 8	33	300	314	137		3.5×6×3.1	24
SREK10	61	300	372	157	12	4.5×7.5×4.1	29
SREK12	67	300	588	274	12	4.5×7.5×4.1	32
SREK13	83	300	686	323		4.5×7.5×4.1	33
SREK16	126	250	882	451		4.5×7.5×4.1	38
SREK20	178	250	1,180	647		5.5×9×5.1	43
SREK25	355	250	1,860	882	15	5.5×9×5.1	51
SREK30	483	200	2,650	1,180		6.6×11×6.1	60

E-15

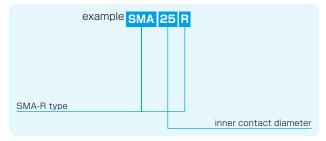
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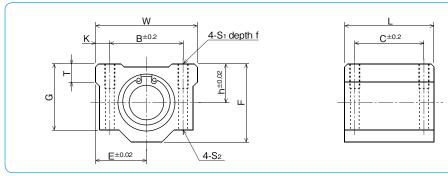
SLIDE ROTARY BUSH

SMA-R TYPE



part number structure





						n	ajor	dime	nsior	IS						basic loa	ad rating	allowable	
nort number	inner conta	ict diameter		0	uter	dime	nsion	s		r	noun	ting o	dimer	sion	s	dynamic	static	revolutions	mass
part number		tolerance	h	Е	W	L	F	G	Т	в	С	κ	S1	f	S ₂	С	Co	per minute	
	mm	μm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm		mm	mm	Ν	Ν	rpm	g
SMA 6R	6	1.4	9	15	30	25	18	15	6	20	15	5	M4	8	3.4	78	176	300	33
SMA 8R	8	+4 -5	11	17	34	30	22	18	6	24	18	5	M4	8	3.4	137	314	300	55
SMA10R	10	-5	13	20	40	35	26	21	8	28	21	6	M5	12	4.3	157	372	300	93
SMA12R	12	+3	15	21	42	36	28	24	8	30.5	26	5.75	M5	12	4.3	274	588	300	104
SMA13R	13	-6	15	22	44	39	30	24.5	8	33	26	5.5	M5	12	4.3	323	686	300	128
SMA16R	16	-0	19	25	50	44	38.5	32.5	9	36	34	7	M5	12	4.3	451	882	250	216
SMA20R	20	+3	21	27	54	50	41	35	11	40	40	7	M6	12	5.2	647	1,180	250	286
SMA25R	25	+3 -7	26	38	76	67	51.5	42	12	54	50	11	M8	18	7	882	1,860	250	645
SMA3OR	30	-/	30	39	78	72	59.5	49	15	58	58	10	M8	18	7	1,180	2,650	200	824
SMA40R	40	+3/-8	40	51	102	90	78	62	20	80	60	11	M10	25	8.7	1,960	4,020	200	1,719
																	11	J≐0 1	02kgf

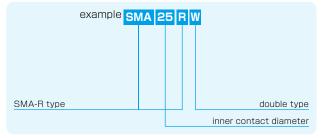
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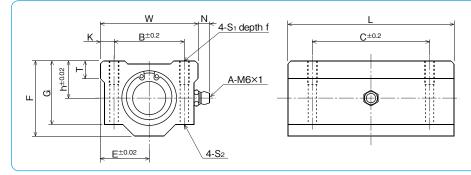
SMA-RW TYPE

-Double-Wide Block type-







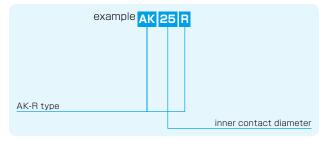


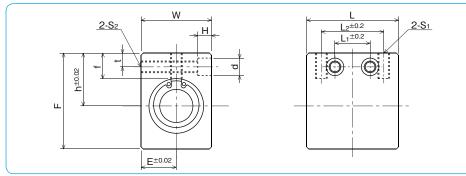
							ma	jor d	imen	ision	S						basic lo	ad rating	allowable	
nort number	inner conta	ct diameter			oute	r din	nens	ions			r	noun	ting (dimer	nsion	s	dynamic	static	revolutions	mass
part number		tolerance	h	Е	W	L	F	G	Т	Ν	в	С	κ	S1	f	S ₂	С	Co	per minute	
	mm	μm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm		mm	mm	Ν	Ν	rpm	g
SMA 6RW	6	1.4	9	15	30	48	18	15	6	7	20	36	5	M4	8	3.4	126	352	300	68
SMA 8RW	8	+4 -5	11	17	34	58	22	18	6	7	24	42	5	M4	8	3.4	222	628	300	113
SMA10RW	10	-5	13	20	40	68	26	21	8	7	28	46	6	M5	12	4.3	254	744	300	188
SMA12RW	12	+3	15	21	42	70	28	24	8	6.5	30.5	50	5.75	M5	12	4.3	444	1,180	300	210
SMA13RW	13	+3 -6	15	22	44	75	30	24.5	8	6.5	33	50	5.5	M5	12	4.3	523	1,370	300	254
SMA16RW	16	-0	19	25	50	85	38.5	32.5	9	6	36	60	7	M5	12	4.3	731	1,760	250	431
SMA20RW	20	+3	21	27	54	96	41	35	11	7	40	70	7	M6	12	5.2	1,050	2,360	250	568
SMA25RW	25	-	26	38	76	130	51.5	42	12	4	54	100	11	M8	18	7	1,430	3,720	250	1,282
SMA30RW	30	-7	30	39	78	140	59.5	49	15	5	58	110	10	M8	18	7	1,910	5,300	200	1,638
SMA40RW	40	+3/-8	40	51	102	175	78	62	20	5	80	140	11	M10	25	8.7	3,180	8,040	200	3,419
																		11	N≒0.1	02kgf

AK-R TYPE -Compact Block type-



part number structure





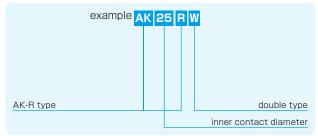
			I					dime	nsior	-						basic lo	ad rating	allowable	
part number	inner conta	ct diameter	0	uter	dime	nsion	IS		. n	noun	ting c	dimer	ision	S		dynamic	static	revolutions	
part number		tolerance	h	Е	W	L	F	L2	S1	f	L1	t	S ₂	d	н	С	Co	per minute	
	mm	μm	mm	mm	mm	mm	mm	mm		mm	mm	mm		mm	mm	Ν	Ν	rpm	g
AK 6R	6	1.4	14	8	16	27	22	18	M4	8	9	5	M4	6	5	78	176	300	27
AK 8R	8	+4 -5	16	10	20	32	26	20	M5	8.5	10	5	M4	6	5	137	314	300	48
AK10R	10	-5	19	13	26	39	32	27	M6	9.5	15	6	M5	8	6	157	372	300	94
AK12R	12	+3	20	14	28	40	34	27	M6	9.5	15	6	M5	8	6	274	588	300	105
AK13R	13	+3 -6	25	15	30	42	43	28	M6	13.5	16	7	M6	9	7	323	686	300	151
AK16R	16	-0	27	18	36	47	49	32	M6	13	18	7	M6	9	7	451	882	250	238
AK20R	20	+3	31	21	42	52	54	36	M8	15	18	8	M8	11	8	647	1,180	250	328
AK25R	25	+3 -7	37	26	52	69	65	42	M10	17	22	9	M10	14	10	882	1,860	250	669
AK3OR	30	-7	40	29	58	74	71	44	M10	17.5	22	9	M10	14	10	1,180	2,650	200	856
																	11	N≑0.1	02kgf

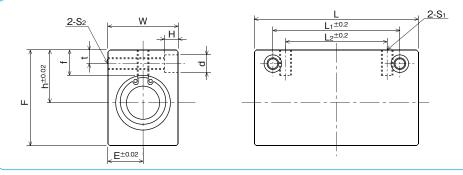
AK-RW TYPE

-Double-Wide Compact Block type-









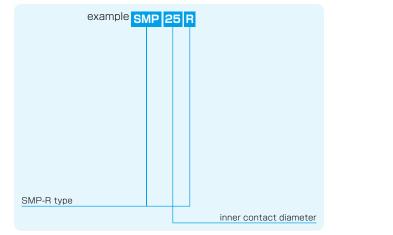
	inner contac	at diamatar		utor	dimo	m nsion		dime		-	tina a	limor	nsion			basic lo	ad rating	allowable	-
part number		tolerance	h	E	W	L	F	L2	S1	f	L1	t	S2	d	н	C		revolutions per minute	
	mm	μm	mm	mm	mm	mm	mm	mm		mm	mm	mm		mm	mm	N	Ν	rpm	g
AK 6RW	6	14	14	8	16	46	22	20	M4	8	30	5	M4	6	5	126	352	300	48
AK 8RW	8	+4 -5	16	10	20	56	26	30	M5	8.5	42	5	M4	6	5	222	628	300	89
AK10RW	10	-5	19	13	26	68	32	36	M6	9.5	50	6	M5	8	6	254	744	300	175
AK12RW	12	+3	20	14	28	70	34	36	M6	9.5	50	6	M5	8	6	444	1,180	300	196
AK13RW	13	-6	25	15	30	74	43	42	M6	13.5	55	7	M6	9	7	523	1,370	300	281
AK16RW	16	-0	27	18	36	84	49	52	M6	13	65	7	M6	9	7	731	1,760	250	450
AK20RW	20	5	31	21	42	94	54	58	M8	15	70	8	M8	11	8	1,050	2,360	250	626
AK25RW	25	+3	37	26	52	128	65	80	M10	17	100	9	M10	14	10	1,430	3,720	250	1,299
AK3ORW	30	-/	40	29	58	138	71	90	M10	17.5	110	9	M10	14	10	1,910	5,300	200	1,662

1N≒0.102kgf

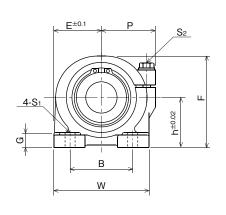
SMP-R TYPE -Pillow Block type-

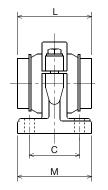


part number structure



				m	ajor dimen	sions			
part number	inner cont	act diameter				outer dir	nensions		
part number		tolerance	h	E	W	L	F	G	М
	mm	μm	mm	mm	mm	mm	mm	mm	mm
SMP13R	13	+3	25	25	50	32	46	8	36
SMP16R	16	-6	29	27.5	55	37	53	10	40
SMP20R	20	+3	34	32.5	65	42	62	12	48
SMP25R	25	-7	40	38	76	59	73	12	59
SMP30R	30	-/	45	42.5	85	64	84	15	69
SMP40R	40	+3/-8	60	62	124	80	112	18	86





Р	mou B	unting din C	nensions S1	adjustment screw size	basic loa dynamic C	ad rating static Co	allowable revolutions per minute	mass	part number
mm	mm	mm	mm	S2	Ν	Ν	rpm	g	
30	30	26	7 (M5)	M5	323	686	300	266	SMP13R
32	35	29	7 (M5)	M5	451	882	250	369	SMP16R
37	40	35	8 (M6)	M6	647	1,180	250	690	SMP20R
43	50	40	8 (M6)	M6	882	1,860	250	970	SMP25R
49	58	46	10 (M8)	M8	1,180	2,650	200	1,420	SMP30R
68	76	64	12 (M10)	M10	1,960	4,020	200	3,585	SMP40R

1N≑0.102kgf

SLIDE ROTARY BUSH RK TYPE

NB's RK type slide rotary bush is a highly accurate and high load capacity bearing providing smooth continuous linear and rotational motions. Its structure imposes no constraints on linear and rotational motions. It is much more compact than a standard slide bush with separate rotational bearing.

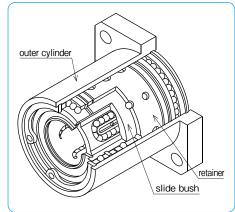
STRUCTURE AND ADVANTAGES

The RK type slide rotary bush uses a retainer similar to that used in the SR type stroke bush. This retainer gives a smooth motion in a high rotational application.

SM type slide bush is incorporated, providing the stable and smooth linear motion.

Relatively large ball elements are used for high load capacity.

Figure E-6 Structure of RK Slide Rotary Bush



- 1. A smooth unlimited linear and rotational motion is obtained.
- 2. There is no need to machine separate housing.
- 3. High accuracy is ensured for extended period of usage.
- 4. Its high compatibility eliminates replacement problems.
- 5. High rigidity enables it to withstand an unbalanced load and large load.

%For best performance, please select tolerance of h5 for the shaft.

Calculation of Life:

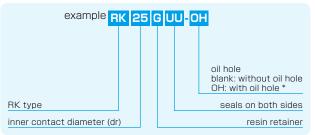
$$L = \left(\frac{f_{H} \cdot f_{T} \cdot f_{C}}{f_{W}} \cdot \frac{C}{P}\right)^{3} \times 50$$

L: rated life (km) fH: hardness coefficient fr: temperature coefficient fc: contact coefficient fw: applied load coefficient C: basic dynamic load rating (N) P: applied load (N) %Refer to page Eng-5 for the coefficients.

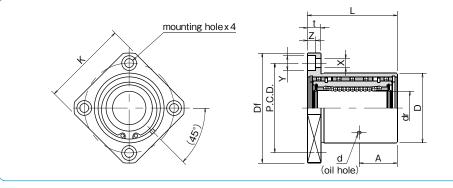
RK TYPE



part number structure



*Oil hole is for rotary-portion lubrication.



						majo	dim	ensi	ons					basic loa	ad rating	allowable	
part number		dr		D		L	Α	d			fl	ange		dynamic	static	revolutions	mass
part number		tolerance		tolerance		tolerance			Df	Κ	t	P.C.D.	X×Y×Z	С	Co	per minute	
	mm	μm	mm	μm	mm	mm	mm	mm	mm	mm	mm	mm	mm	N	Ν	rpm	g
RK12GUU	12	0	32	0	36		15	2	54	42	8	43	5.5×9×5.1	510	784	500	180
RK16GUU	16	- 9	40	-25	45		19.5	2	62	50	8	51	5.5×9×5.1	774	1,180	500	280
RK20GUU	20	0	45	-25	50	±0.3	21.5	3	74	58	10	60	6.6×11×6.1	882	1,370	400	420
RK25GUU	25	-10	52	0	67		28.5	3	82	64	10	67	6.6×11×6.1	980	1,570	400	680
RK30GUU	30	-10	60	-30	74		31	3	96	75	13	78	9×14×8.1	1,570	2,740	400	990
																111-0	1001.~4

1N≒0.102kgf

SLIDE ROTARY BUSH FR/FRATYPE

NB Slide Rotary Bush FR type provides combined functions of linear and rotary motion without stroke limitation. Unlike the traditional slide bush, ball elements are arranged around the shaft within the inner space of a bush maintaining compact dimensions while providing high load capacity and high rigidity.

STRUCTURE AND ADVANTAGES

FR type is supplied as a set of a bush and shaft. Constructed with combination of a load carrying outer cylinder and a return cap, it is designed for smooth compound motions. For ease of mounting, the FRA type is also available, which has the FR bush preinstalled within a factory made housing.

High Load Capacity, High Rigidity

High load capacity, high rigidity, and long life are achieved by ball elements placed all around the inner space between an outer cylinder and a linear shaft.

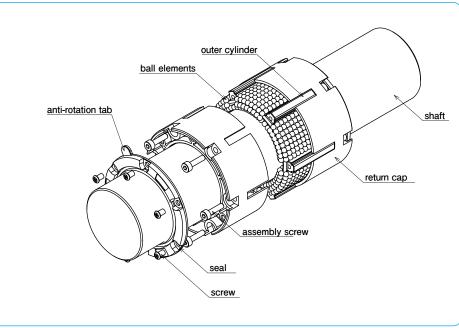
Smooth Motion

Although it is an all-ball bearing construction, load carrying balls are designed to align along the linear direction to provide smooth motion in both linear and rotational directions.

High Accuracy

Each set of a bush and shaft is matched and controlled to ensure smooth and highly accurate motion.

Figure E-7 Structure of FR type



RATED LIFE AND LOAD RATING

The rated life and load rating are defined as follows.

Rated Life

When a group of slide rotary bushing of the same type are used under the same conditions, the rated life is the number of rotations achieved by 90% of the group without causing flaking.

Basic Dynamic Load Rating

The basic dynamic load rating is the dynamic load with a constant direction and magnitude at which a rated life of 106 rotations can be achieved.

Basic Static Load Rating

The basic static load rating is the static load with a constant direction that would result in a certain contact stress at the mid-point of the ball elements and tracking surface that are experiencing the maximum stress.

Equation (1) gives the relation between the applied load and the rated life of Slide Rotary Bush.



L: rated life (106 rotations) fc: contact coefficient (Table E-4) fw: applied load coefficient (Table E-5) C: basic dynamic load rating (N) P: applied load (N)

Table E-4 Contact Coefficient

number of linear in close contact of	contact coefficient fc
1	1.00
2	0.81
3	0.72
4	0.66
5	0.61

Table E-5	Applied	Load	Coefficient
-----------	---------	------	-------------

operating conditions								
velocity	coefficient fw							
15m/min or less	1.0~1.5							
40m/min or less	1.5~2.0							
40m/min or less	2.0~3.5							
	velocity 15m/min or less 40m/min or less							

<u>3.5</u>

Since the slide rotary bush is used in combined linear and rotary motion, the life time is obtained using Equations (2) and (3).

•When linear and rotary motions are combined

$$L_{h} = \frac{10^{6} \cdot L}{60\sqrt{(dm \cdot n)^{2} + (10 \cdot S \cdot n_{1})^{2}/dm}} \cdots (2)$$

When only linear motion is involved

$$L_{h} = \frac{10^{6} \cdot L}{600 \cdot S \cdot n_{1}/(\pi \cdot dm)} \quad \dots \dots \dots \dots \dots (3)$$

Lh: life time (hr) S: stroke length (mm) n: revolutions per minute (rpm) n1: number of cycles per minute (cpm)dm: ball pitch diameter (mm) \doteq 1.07dr (dr is the inner contact diameter of FR type)

HOUSING

NB Slide Rotary Bush FR type is manufactured with a properly controlled clearance between the shaft and the bush. When designing a custom housing, the recommended tolerance for the housing bore is H7 or H6. When rotational motion is involved anti-rotation tab option (Z) is recommended to prevent the bush from rotating within the housing.

Please refer to Table E-6 for the recommended dimensions of housing when using the anti-rotation tab. FRA type is provided with anti-rotation tab as standard feature.

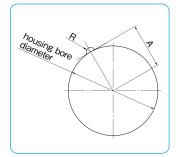


Table E-6

p

	recommended dimensions												
oart number	housing bo	re diameter	F	А									
		tolerance		tolerance									
	mm	mm	mm	mm	mm								
FR20	32	+0.025	1.75		16								
FR25	40	+0.025	2.25	+0.1	20								
FR30	45	0	2.20	+0.1	22.5								
FR40	60	+0.030	2.75	0	30								
FR50	80	0	4		40								

USE AND HANDLING PRECAUTIONS

Ball Drop

FR type is a set of a bush and shaft. Ball elements will drop out if the bush is removed from the shaft since the balls are not retained inside the cylinder. When FR bush must be removed from the shaft, please use a temporary shaft identical to the FR shaft diameter.

Lubrication

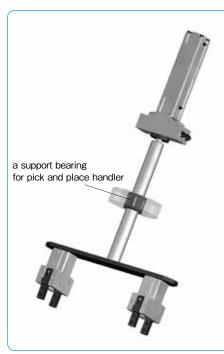
The purpose of lubrication includes the reduction of friction among the rolling elements as well as between the rolling elements and the raceway, prevention of sintering, reduction of wear, and the prevention of rust. To maximize the performance of FR type, the lubricant type and lubrication method should be selected properly according to the operating conditions. The FR type is pre-lubricated with lithium soap based grease No. 0 for immediate use. Please relubricate with a similar type of grease depending on the operating conditions.

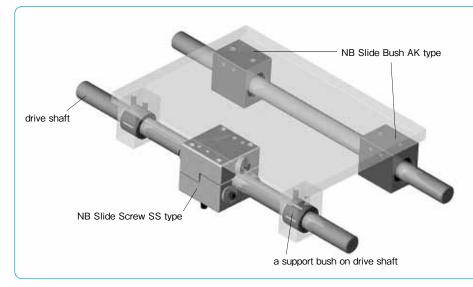
Operating Temperature Range

FR type's allowable temperature range is from -20 to 80 degrees Celsius.

APPLICATION EXAMPLES



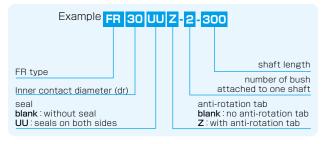


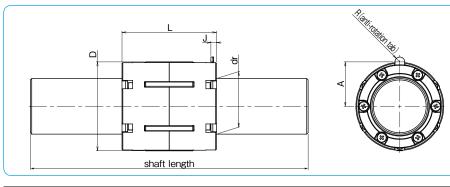


FR TYPE



part number structure





				majo	basic lo	*2										
part number	inner contact	D*1		1	L		R		J	dynamic	static	revolutions	speed	mass		
part number	diameter dr		tolerance		tolerance		tolerance				Co	per minute				
	mm	mm µm		mm	mm	mm	mm	mm	mm	N	N	rpm	m/min	g		
FR20	20	32	0 16	34	0 1.	1.75	16	2	1,910	3,010	2,000		55			
FR25	25	40		41	-0.5	2.25		20	2.4	3,130 4,780	1,500		105			
FR30	30	45		42	0 -0.6	2.25 2.75 4	-	-	0 -0.2	22.5	2.5	3,570	5,750	1,000	40	122
FR40	40	60	0	56	0 -0.7				30	3	6,970	10,600	800		302	
FR50	50	80	-19	74	0 -1			40	3	13,500	18,800			885		

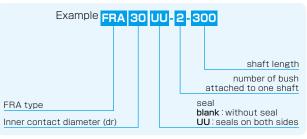
E-28

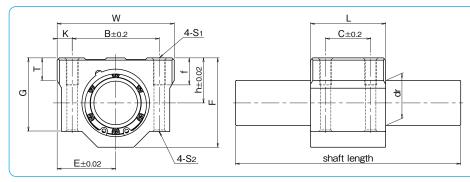
*1 : excluding resin part

*2 : excluding shaft

part number structure

FRA TYPE





	major dimensions														basic load rating allowable allowable *					
part number	inner contact diameter dr		Е	w	L	F	G	т	В	С	к	S1	f	S2	dynamic C		revolutions per minute		mass	
	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm		mm	mm	N	Ν	rpm	m/min	g	
FRA20	20	21	27	54	40	41	35	11	40	25	7	M6	12	5.2	1,910	3,010	2,000		170	
FRA25	25	26	38	76	50	51.5	42	12	54	30	11	140	10	7	3,130	4,780	1,500		360	
FRA30	30	30	39	78	50	59.5	49	15	58	30	10	IVIO	M8 18	1	3,570	5,750	1,000		420	
FRA40	40	40	51	102	65	78	62	20	80	40	11	M10	10 25	5 8.7	0.7	6,970	10,600	800		950
FRA50	50	52	61	122	84	102	80	25	100	50	11	M10 2			13,500	18,800			2,120	

*1 : excluding shaft