1. Specifications

Driver Name	**SBDM-10A**	**SBDM-25A**
Maximum Allowable Current	10A	25A
Input Voltage	DC 12 ~ 24 V ±15%	
Speed Control Range	300~3000 RPM	
Insulation Resistance	Measured value of 100MΩ at DC500V Mega Input Columns	
Environment	Ambient temperature 0℃ ~ 50℃ (Is not freezing)	
Speed Settings	External speed setting	
Protection	Overload / Incorrect connection -> Motor Stop	

2. Functions

2-1) Display

Power	- PW LED will light when you connect the power.
Fault	- FLT LED will light when the driver Incorrect connection, low voltage, overload
ALARM	- ALM LED lights come on when the overload. And the output is low.

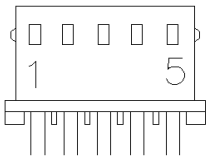
2-2) U/I

②Dir. Out	- HIGH signal is output on CW and vice versa. (Open collector signal)
③ALARM Out	- When protective function (over current, misconnection, Motor fault) is acted, LED is turned on and motor is stopped of itself, then alarm is out
④SPEED Out	- Pulse output is proportional to speed. - 60□: 6pulse/rev, 80□, 90□: 18 pulse/rev, SL: 12 pulse/rev.
⑤ALARM RESET	- When OC LED is turned on, Every condition becomes clear pushing the button..
⑥Direction	- Direction of rotation is changed when F/R pin is connected to GND ※ What the direction is changed at a high speed condition is so dangerous. (Please contact to us.)
⑦Brake	- Free if Brk pin is connected to GND and vice versa. - Block of the motor current is flowing.(Dynamic brake) ※ This is an option. If you need this function, please contact to us.
⑧Run/Stop(A)	- R / S terminal GND and contact Run, non-contact Stop. - Model back (A).
⑧Run/Stop(B)	- R / S terminal GND and non-contact Run, contact Stop - Model back (B).
⑨⑩⑪SPEED	- Please keep the voltage level under 5V when using another voltage source. - CW is the direction increasing a speed when using a variable resistance at #9,10,11 of U/I Connector.
Slow Start/Down	- Variable resistor VR1 (variable resistor is attached to the driver board) by adjusting You can adjust the speed of the motor response - Clockwise direction, the reaction speed is slow. ※This feature controls the variable resistor must be reset after power is applied

※ If you exceed the maximum voltage 30V driver may be damaged..

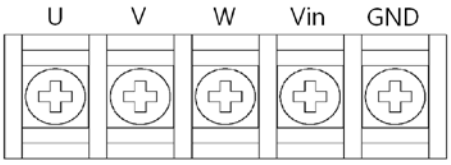
3. Connector Specifications

3-1) Hall (Driver : 5267-05, Housing : 5264-05)



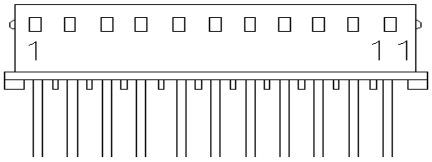
1	2	3	4	5
Hu	Hv	Hw	GND	Vcc
Hall Sensor				
Hall U	Hall V	Hall W	Ground	Power

3-2) Motor & Power

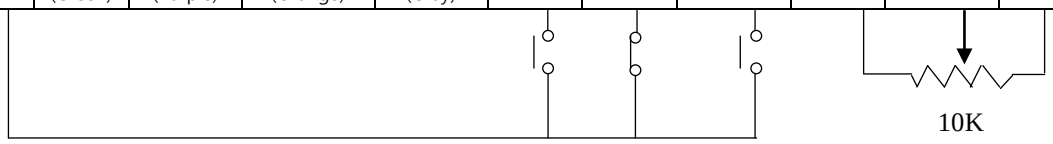


U	V	W	Vin	GND
Motor Power			DC12~24V Power Input	

3-3) User Interface (Driver : 5267-11, Housing : 5264-11)



1	2	3	4	5	6	7	8	9	10	11
COM (Black)	Dir Out (Green)	Alarm Out (Purple)	Speed Out (Orange)	Alarm Reset (Gray)	F/R (Brown)	BRK (White)	R/S (pink)	GND (blue)	Speed (yellow)	+5V (red)

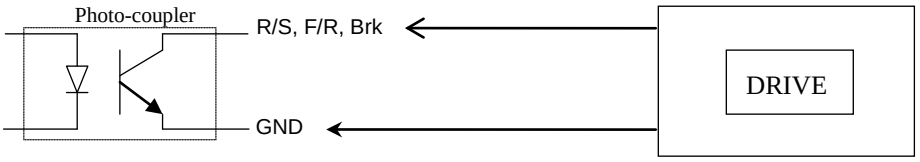


※Tip. Black(1)+white(7)+pink(8) after the connection speed, turn the variable resistor in a clockwise direction = CCW rotation

Black(1)+white(7)+pink(8)+brown(6) after the connection speed, turn the variable resistor clockwise direction = CW rotation

4. Interface with another controller

F/R, R/S, Brk

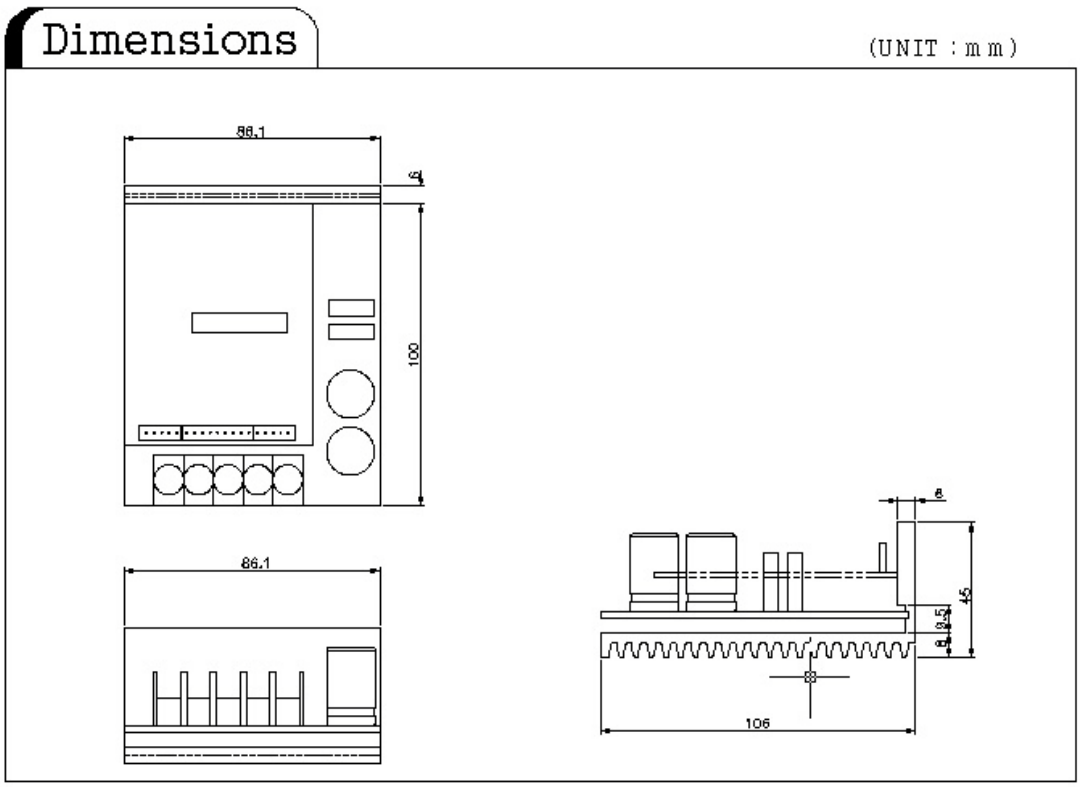


Speed Command

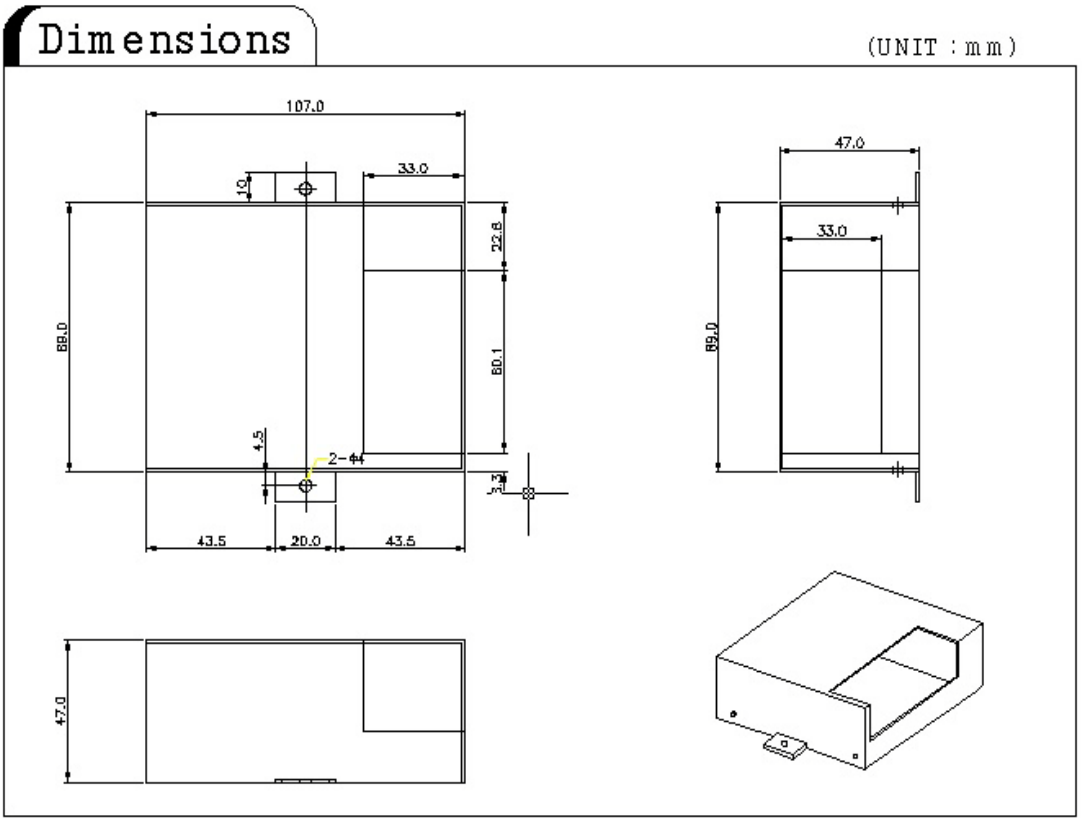
Put Analog voltage(0~5V) into #10 pin of U/I Connector.

5. Dimension

5-1) Heatsink Dimension



5-2) Case Dimension



6. Motor & Driver Connection